

# **Automated Braking** Innovations **Brake Pedal Testing System**

#### Members:

Riley Lytwynec, Benjamin Newland, Danial Rutkowski, and Nick Sadro

#### **Faculty Advisors:**

Prof. Dave McDonald Mr. David Leach **Company:** Continental

# **Industrial Contacts:**

Mr. Dan Goodrich Mr. Travis Smith

#### Presentation: 2 pm | CAS 212 Demonstration: 2:30 pm | CAS 106C

Team Automated Braking Innovations (ABI) is designing and building an automated brake pedal applier for Continental Automotive's hardware-inloop systems. Currently, Continental uses these hardware-in-loop systems to test brake systems, but the system must have a human operator to apply the brake pedal. Team ABI's unit will be used to automate the brake testing process by controlling the position of the pedal and how much force is applied.



# **Adexobot-Vision Integration Solution** Versatile Robotics **Grocery Bagging System**

### Members:

Rob Kalinski, Josh Nelson, Brian Parkham, Nathan Shoudy, and Dion Tchokreff

#### **Faculty Advisors:**

Prof. Jim Devaprasad Dr. Paul Weber **Company:** Advenovation Industrial Contact: Mr. Adil Shafi

Presentation: 2:30 pm | CAS 212 Demonstration: 3 pm | CAS 125

Team Adexobot - Vision Integration Solution (A-VIS) has been tasked with developing a proof-of-concept system to mimic an automated grocery bagger. The bagger consists of a robot working with a machine vision system and a versatile gripping device. This robotic bagging system will handle a variety of household items such as grocery boxes, cans, and bottles. This project will provide an automation solution that is unique to the robotics industry in its versatility and simplicity of use.



# **Laser Control Solutions** Self-Leveling Mill Head

### **Members:**

Jacob Clark, Logan Cowley, Josh Houska, Steven Jacobs, and Eric Stephan

# **Faculty Advisor:**

Dr. David Baumann **Company:** Mactech

# **Industrial Contacts:**

Mr. Sam Schammel Mr. Paul Rulach Mr. Joel Wittenbraker

#### Presentation: 3 pm | CAS 123 Demonstration: 3:30 pm | SmartZone

Team Laser Control Solutions (LCS) is working alongside Mactech On-Site Machining Solutions to develop and test a real-time self-leveling system for their Large Diameter Facing Machine (LDFM). The LDFM is used to machine large diameter flanges (6'-18') for the oil, marine, and power industries. The goal of this project is to reduce overall machining tolerances from .015" to .005" using a laser measurement system and a custom designed control loop.



# **Locomotive Onsite Communication Initiative** Loci Automation

#### Members:

Ronald Biron, Stephanie Peck, Niels-Erik Rayn, and David Vikken Faculty Advisor: Dr. Joe Moening

**Company:** Essar Steel Algoma, Inc. **Industrial Contacts:** 

Mr. Denis Cesarin Mr. David Clingen

#### Presentation: 2 pm | CAS 123 Demonstration: 2:30 pm | CAS 125

Team Locomotive Onsite Communication Initiative (LOCI) has thoroughly tested a radar based position sensor to be implemented in a proximity warning system for the locomotives (loci) used in the coke making process at Essar Steel Algoma Inc. The primary goal of this project was to determine if the position sensor could operate through steam, snow, ice, as well as under other harsh environmental conditions. This project is phase one of a longer term project of completely automating the loci.



#### Members:

and Spencer Thomas **Faculty Advisor:** Dr. Robert Hildebrand

**Marine Refueling Concepts** Liquefied Natural Gas **Bunkering Barge** 

Robert Klein, Steven Krentz, Tyler Pavelich, Michael Richardson, **Company:** Moran Iron Works, Inc.

Industrial Contact: Mr. Victor Ruppert

Presentation: 1:30 pm | CAS 212 Demonstration: 2 pm | CAS 120

Team Marine Refueling Concepts (MRC) conducted a feasibility study and conceptual design of an LNG (liquefied natural gas) bunkering barge, for Moran Iron Works of Onaway, which would refuel an anticipated fleet of Great Lakes vessels operating on LNG fuel. Design efforts focused on economic scaling of the barge, layout of refueling tanks and equipment, and capsize stability in Great Lakes waves, allowing for LNG sloshing in tanks, the latter phenomenon studied by simulation and wave tank experiments.



# **Railway Automation** Solutions **Robotics Fluid Dispensing** with Machine Vision

#### **Members:**

Kevin Danhof, Randy Gee, Taylor Heath, Karl Larsen, and Levi Marchetti

# **Faculty Advisor:**

Jon Coullard **Company:** Pre-tec **Industrial Contact:** 

Mr. Jeff Johnston

Presentation: 1:30 pm | CAS 123 Demonstration: 2 pm | CAS 124

Team Railway Automation Solutions (RAS) designed and implemented a robotics workcell to simulate the dispensing of Spikefast, a wood filler product, into railroad ties. A Motoman robot, using custom end of arm tooling and a machine vision system, locates the positions of spike holes on railroad ties as they move by on a continuous conveyor. This project serves as a proof of concept for future development of a wood product dispensing system in the railroad industry.



#### **Solar Film Innovations**

# Window-Based Photovoltaic Systems

#### Members:

Greg Balcom, Victor Duffrin, Brandyn Everest, Mitchell Paradis, Apury Shanker, and Randi Sims (co-op student, fall 2013)

#### **Faculty Advisors:**

Dr. Jaskirat Sodhi Dr. Paul Weber

# **Companies:**

3M, Little Traverse Conservancy

#### **Industrial Contacts:**

Mr. Tim Hebrink Mr. Charles Dawley

### Presentation: 3 pm | CAS 212 Demonstration: 3:30 pm | CAS 212

Team SFI designed and built two window-based solar systems, utilizing 3M Brand Prestige Series Window Film to reflect near infrared light onto photovoltaic cells. This not only allows for increased power output, but also provides room temperature and shading control while allowing visible light through the window. The first system is an improvement on a previous senior project, and replaces an entire window. The second system is a new design, which replaces window-mounted blinds.



# Industrial Technology **Directed Senior Project**

Member: Brian Horn Faculty Advisor: Jeff King **Customer:** LSSU Industrial Contact: Dr. Joe Moening Presentation: 3:30 pm | CAS 123 Demonstration: 4 pm | CAS 125

This project updates lab equipment (Part Checker) for the EGRS365 course to use a current generation Allen-Bradley PLC and HMI. Determining hardware, ordering and implementation of the hardware, and testing the updated equipment are required for completion of the project.



# **ENGINEERING HOUSE Faculty Advisors:**

Dr. Joe Moening Dr. Jaskirat Sodhi

#### Presentation: 2:30 pm | CAS 212 Demonstration: 3 pm | CAS 310

The Engineering Living Learning Community (Engineering House) designed and built a 3D printer at a significantly lower cost than LSSU's current 3D printer. The new device will be used to print souvenirs for Robotics summer camps. Many avenues were explored to reduce the component cost as well as the operating costs. Off-theshelf components were used where possible, with remaining components machined by the students.

# Welcome to the School of **Engineering & Technology**

# **1:30 p.m.**

Presentations: Team RAS CASET 123 CASET 212 Team MRC

# **2:00 p.m.**

Presentations: Team LOCI CASET 123 CASET 212 Team ABI Demonstrations: CASET 120 Team MR C CASET 124 Team RAS

# **2:30** p.m.

Presentations: CASET 123 Team A-VIS CASET 212 Engineering House Demonstrations: CASET 106C Team ABI CASET 125 Team LOCI

#### **3:00 p.m.** Presentations:

CASET 123 Team LCS CASET 212 Team SFI Demonstrations: CASET 310 Engineering House CASET 125 A-VIS

# **3:30 p.m.**

Presentations: CASET 123 Brian Horn Demonstrations: CASET 212 Team SFI SmartZone Team LCS The SmartZone building is located at 2345 Meridian Street

4:00 p.m. Demonstration: CASET 125 Brian Horn

Students will be available throughout the afternoon for informal demonstrations and questions. The Engineering Living Learning Community House (Chippewa Hall) will be open for tours.

# 2013-14 Senior Projects Faculty Board Members

This group serves as advisors, overseers, and guides to help the teams through their overall process: Jim Devaprasad (chair), David Baumann, Jon Coullard, Robert Hildebrand, Jeff King, David McDonald, Joe Moening, Jaskirat Sodhi, and Paul Weber

Special thanks to Eric Becks, Laura Bofinger, David Leach, and Jeanne Shibley

# The School of Engineering & Technology comprises the following disciplines:

• Computer Engineering • Electrical Engineering

- Industrial Technology
- Manufacturing Engineering Technology
- Electrical Engineering Technology
- Mechanical Engineering

All of the Lake Superior State University senior engineering and engineering technology bachelor's students are required to complete a challenging senior design project. The students work in multidisciplinary teams and use a composite of their technical and general education courses to successfully complete these projects.

The intention of the senior design project is to provide valuable engineering experience that will help students transition from academia to industry or graduate school. Each project requires a detailed technical engineering analysis, development and follow-through to provide a realistic experience for our graduates.

For more information about LSSU's School of Engineering & Technology www.lssu.edu/eng or 906-635-2207





# The School of Engineering & Technology

presents the

# **Class of 2014 Senior Design Project Presentations** & Demonstrations



Friday • May 2, 2014 1:30 p.m. - 5:00 p.m. in the Center for Applied Science and **Engineering Technology**